# Lie Groups, Physics and Geometry 

Robert Gilmore

Many years ago I wrote the book Lie Groups, Lie Algebras, and Some of Their Applications (NY: Wiley, 1974). That was a big book: long and difficult. Over the course of the years I realized that more than $90 \%$ of the most useful material in that book could be presented in less than $10 \%$ of the space. This realization was accompanied by a promise that some day I would do just that - rewrite and shrink the book to emphasize the most useful aspects in a way that was easy for students to acquire and to assimilate. The present work is the fruit of this promise.

In carrying out the revision I've created a sandwich. Lie group theory has its intellectual underpinnings in Galois theory. In fact, the original purpose of what we now call Lie group theory was to use continuous groups to solve differential (continuous) equations in the spirit that finite groups had been used to solve algebraic (finite) equations. It is rare that a book dedicated to Lie groups begins with Galois groups and includes a chapter dedicated to the applications of Lie group theory to solving differential equations. This book does just that. The first chapter describes Galois theory, and the last chapter shows how to use Lie theory to solve some ordinary differential equations. The fourteen intermediate chapters describe many of the most important aspects of Lie group theory and provide applications of this beautiful subject to several important areas of physics and geometry.

Over the years I have profitted from the interaction with many students through comments, criticism, and suggestions for new material or different approaches to old. Three students who have contributed enormously during the past few years are Dr. Jairzinho Ramos-Medina, who worked with me on Chapter 15 (Maxwell's Equations), and Daniel J. Cross and Timothy Jones, who aided this computer illiterate with much moral and ebit ether support. Finally, I thank my beautiful wife Claire for her gracious patience and understanding throughout this long creation process.

## Contents

1 Introduction ..... page 1
1.1 The Program of Lie ..... 1
1.2 A Result of Galois ..... 3
1.3 Group Theory Background ..... 4
1.4 Approach to Solving Polynomial Equations ..... 9
1.5 Solution of the Quadratic Equation ..... 10
1.6 Solution of the Cubic Equation ..... 12
1.7 Solution of the Quartic Equation ..... 15
1.8 The Quintic Cannot be Solved ..... 18
1.9 Example ..... 19
1.10 Conclusion ..... 22
1.11 Problems ..... 23
2 Lie Groups ..... 25
2.1 Algebraic Properties ..... 25
2.2 Topological Properties ..... 27
2.3 Unification of Algebra and Topology ..... 29
2.4 Unexpected Simplification ..... 31
2.5 Conclusion ..... 31
2.6 Problems ..... 32
3 Matrix Groups ..... 37
3.1 Preliminaries ..... 37
3.2 No Constraints ..... 39
3.3 Linear Constraints ..... 39
3.4 Bilinear and Quadratic Constraints ..... 42
3.5 Multilinear Constraints ..... 46
3.6 Intersections of Groups ..... 46
3.7 Embedded Groups ..... 47
3.8 Modular Groups ..... 48
3.9 Conclusion ..... 50
3.10 Problems ..... 50
4 Lie Algebras ..... 61
4.1 Why Bother? ..... 61
4.2 How to Linearize a Lie Group ..... 63
4.3 Inversion of the Linearization Map: EXP ..... 64
4.4 Properties of a Lie Algebra ..... 66
4.5 Structure Constants ..... 68
4.6 Regular Representation ..... 69
4.7 Structure of a Lie Algebra ..... 70
4.8 Inner Product ..... 71
4.9 Invariant Metric and Measure on a Lie Group ..... 74
4.10 Conclusion ..... 76
4.11 Problems ..... 76
5 Matrix Algebras ..... 82
5.1 Preliminaries ..... 82
5.2 No Constraints ..... 83
5.3 Linear Constraints ..... 83
5.4 Bilinear and Quadratic Constraints ..... 86
5.5 Multilinear Constraints ..... 89
5.6 Intersections of Groups ..... 89
5.7 Algebras of Embedded Groups ..... 90
5.8 Modular Groups ..... 91
5.9 Basis Vectors ..... 91
5.10 Conclusion ..... 93
5.11 Problems ..... 93
6 Operator Algebras ..... 98
6.1 Boson Operator Algebras ..... 98
6.2 Fermion Operator Algebras ..... 99
6.3 First Order Differential Operator Algebras ..... 100
6.4 Conclusion ..... 103
6.5 Problems ..... 104
$7 \quad$ EXPonentiation ..... 110
7.1 Preliminaries ..... 110
7.2 The Covering Problem ..... 111
7.3 The Isomorphism Problem and the Covering Group ..... 116
7.4 The Parameterization Problem and BCH Formulas ..... 121
7.5 EXPonentials and Physics ..... 127
7.5.1 Dynamics ..... 127
7.5.2 Equilibrium Thermodynamics ..... 129
7.6 Conclusion ..... 132
7.7 Problems ..... 133
8 Structure Theory for Lie Algebras ..... 145
8.1 Regular Representation ..... 145
8.2 Some Standard Forms for the Regular Representation 146
8.3 What These Forms Mean ..... 149
8.4 How to Make This Decomposition ..... 152
8.5 An Example ..... 153
8.6 Conclusion ..... 154
8.7 Problems ..... 154
9 Structure Theory for Simple Lie Algebras ..... 157
9.1 Objectives of This Program ..... 157
9.2 Eigenoperator Decomposition - Secular Equation ..... 158
9.3 Rank ..... 161
9.4 Invariant Operators ..... 161
9.5 Regular Elements ..... 164
9.6 Semisimple Lie algebras ..... 166
9.6.1 Rank ..... 166
9.6.2 Properties of Roots ..... 166
9.6.3 Structure Constants ..... 168
9.6.4 Root Reflections ..... 169
9.7 Canonical Commutation Relations ..... 169
9.8 Conclusion ..... 171
9.9 Problems ..... 173
10 Root Spaces and Dynkin Diagrams ..... 179
10.1 Properties of Roots ..... 179
10.2 Root Space Diagrams ..... 181
10.3 Dynkin Diagrams ..... 185
10.4 Conclusion ..... 189
10.5 Problems ..... 191
11 Real Forms ..... 194
11.1 Preliminaries ..... 194
11.2 Compact and Least Compact Real Forms ..... 197
11.3 Cartan's Procedure for Constructing Real Forms ..... 199
11.4 Real Forms of Simple Matrix Lie Algebras ..... 200
11.4.1 Block Matrix Decomposition ..... 201
11.4.2 Subfield Restriction ..... 201
11.4.3 Field Embeddings ..... 204
11.5 Results ..... 204
11.6 Conclusion ..... 205
11.7 Problems ..... 206
12 Riemannian Symmetric Spaces ..... 213
12.1 Brief Review ..... 213
12.2 Globally Symmetric Spaces ..... 215
12.3 Rank ..... 216
12.4 Riemannian Symmetric Spaces ..... 217
12.5 Metric and Measure ..... 218
12.6 Applications and Examples ..... 219
12.7 Pseudo Riemannian Symmetic Spaces ..... 222
12.8 Conclusion ..... 223
12.9 Problems ..... 224
13 Contraction ..... 232
13.1 Preliminaries ..... 233
13.2 Inönü-Wigner Contractions ..... 233
13.3 Simple Examples of Inönü-Wigner Contractions ..... 234
13.3.1 The Contraction $S O(3) \rightarrow I S O(2)$ ..... 234
13.3.2 The Contraction $S O(4) \rightarrow I S O(3)$ ..... 235
13.3.3 The Contraction $S O(4,1) \rightarrow I S O(3,1)$ ..... 237
13.4 The Contraction $U(2) \rightarrow H_{4}$ ..... 239
13.4.1 Contraction of the Algebra ..... 239
13.4.2 Contraction of the Casimir Operators ..... 240
13.4.3 Contraction of the Parameter Space ..... 240
13.4.4 Contraction of Representations ..... 241
13.4.5 Contraction of Basis States ..... 241
13.4.6 Contraction of Matrix Elements ..... 242
13.4.7 Contraction of BCH Formulas ..... 242
13.4.8 Contraction of Special Functions ..... 243
13.5 Conclusion ..... 244
13.6 Problems ..... 245
14 Hydrogenic Atoms ..... 250
14.1 Introduction ..... 251
14.2 Two Important Principals of Physics ..... 252
14.3 The Wave Equations ..... 253
14.4 Quantization Conditions ..... 254
14.5 Geometric Symmetry $S O(3)$ ..... 257
14.6 Dynamical Symmetry $S O(4)$ ..... 261
14.7 Relation With Dynamics in Four Dimensions ..... 264
14.8 DeSitter Symmetry $S O(4,1)$ ..... 266
14.9 Conformal Symmetry $S O(4,2)$ ..... 270
14.9.1 Schwinger Representation ..... 270
14.9.2 Dynamical Mappings ..... 271
14.9.3 Lie Algebra of Physical Operators ..... 274
14.10 Spin Angular Momentum ..... 275
14.11 Spectrum Generating Group ..... 277
14.11.1 Bound States ..... 278
14.11.2 Scattering States ..... 279
14.11.3 Quantum Defect ..... 280
14.12 Conclusion ..... 281
14.13 Problems ..... 282
15 Maxwell's Equations ..... 293
15.1 Introduction ..... 294
15.2 Review of the Inhomogeneous Lorentz Group ..... 295
15.2.1 Homogeneous Lorentz Group ..... 295
15.2.2 Inhomogeneous Lorentz Group ..... 296
15.3 Subgroups and Their Representations ..... 296
15.3.1 Translations $\{I, a\}$ ..... 297
15.3.2 Homogeneous Lorentz Transformations ..... 297
15.3.3 Representations of $S O(3,1)$ ..... 298
15.4 Representations of the Poincaré Group ..... 299
15.4.1 Manifestly Covariant Representations ..... 299
15.4.2 Unitary Irreducible Representations ..... 300
15.5 Transformation Properties ..... 305
15.6 Maxwell's Equations ..... 308
15.7 Conclusion ..... 309
15.8 Problems ..... 310
16 Lie Groups and Differential Equations ..... 320
16.1 The Simplest Case ..... 322
16.2 First Order Equations ..... 323
16.2.1 One Parameter Group ..... 323
16.2.2 First Prolongation ..... 323
16.2.3 Determining Equation ..... 324
16.2.4 New Coordinates ..... 325
16.2.5 Surface and Constraint Equations ..... 326
16.2.6 Solution in New Coordinates ..... 327
16.2.7 Solution in Original Coordinates ..... 327
16.3 An Example ..... 327
16.4 Additional Insights ..... 332
16.4.1 Other Equations, Same Symmetry ..... 332
16.4.2 Higher Degree Equations ..... 333
16.4.3 Other Symmetries ..... 333
16.4.4 Second Order Equations ..... 333
16.4.5 Reduction of Order ..... 335
16.4.6 Higher Order Equations ..... 336
16.4.7 Partial Differential Equations: Laplace's Equation ..... 337
16.4.8 Partial Differential Equations: Heat Equation338
16.4.9 Closing Remarks ..... 338
16.5 Conclusion ..... 339
16.6 Problems ..... 341
Bibliography ..... 347
Index ..... 351

